

Find out the difference(s)?

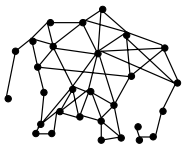


Shape 1

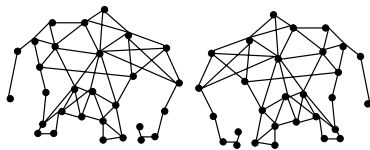


Shape 2

Find out the difference(s)?



Graph G_1



Graph G_2



Programa de Pós-graduação em
INFORMÁTICA



PUC Minas



Graph-based image processing

— Connectivity in graphs —

(Professor version)

(Connectivity in graphs)

Silvio Guimarães

Graduate Program in Informatics – PPGINF

Image and Multimedia Data Science Laboratory – IMScience

Pontifical Catholic University of Minas Gerais – PUC Minas

Outline of the lecture

1 Path

2 Connectivity

3 Algorithms

4 Degrees



Programa de Pós-graduação em
INFORMÁTICA



PUC Minas



Graph-based image processing

— Path —

(Professor version)

(Connectivity in graphs)

Silvio Guimarães

Graduate Program in Informatics – PPGINF

Image and Multimedia Data Science Laboratory – IMScience

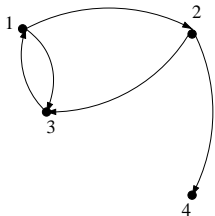
Pontifical Catholic University of Minas Gerais – PUC Minas

Definition

- ▶ Let $G = (E, \Gamma)$ be a graph, and let x and y be two vertices in E
- ▶ A **path from x to y (in G)** is a sequence $\pi = (x_0, \dots, x_\ell)$ of vertices in E such that
 - ▶ $\forall i \in \{1, \dots, \ell\}, x_i \in \Gamma(x_{i-1})$
 - ▶ $x_0 = x$ and $x_\ell = y$

Definition

- ▶ Let $G = (E, \Gamma)$ be a graph, and let x and y be two vertices in E
- ▶ A **path from x to y (in G)** is a sequence $\pi = (x_0, \dots, x_\ell)$ of vertices in E such that
 - ▶ $\forall i \in \{1, \dots, \ell\}, x_i \in \Gamma(x_{i-1})$
 - ▶ $x_0 = x$ and $x_\ell = y$

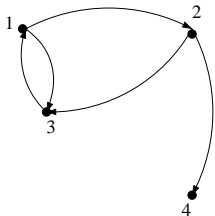


Example

$\pi = (1, 2, 3)$ is a path

Definition

- ▶ Let $G = (E, \Gamma)$ be a graph, and let x and y be two vertices in E
- ▶ A **path from x to y (in G)** is a sequence $\pi = (x_0, \dots, x_\ell)$ of vertices in E such that
 - ▶ $\forall i \in \{1, \dots, \ell\}, x_i \in \Gamma(x_{i-1})$
 - ▶ $x_0 = x$ and $x_\ell = y$
- ▶ If $\pi = (x_0, \dots, x_\ell)$ is a path, ℓ is called its **length**

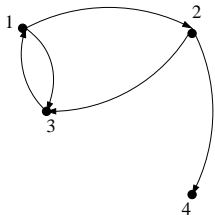


Example

$\pi = (1, 2, 3)$ is a path of length 2

Some remarkable paths

- ▶ A path of length 0 is called a **trivial path**

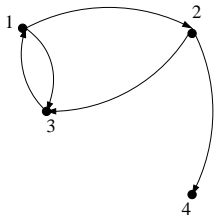


Example

- ▶ (3) is a *trivial path*

Some remarkable paths

- ▶ A path of length 0 is called a **trivial path**
- ▶ A non-trivial path $\pi = (x_0, \dots, x_\ell)$ is called a **circuit** if $x_0 = x_\ell$

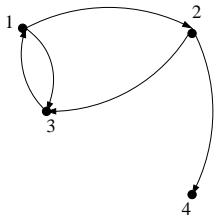


Example

- ▶ (3) is a trivial path
- ▶ $(1, 2, 3, 1)$ is a circuit

Some remarkable paths

- ▶ A path of length 0 is called a **trivial path**
- ▶ A non-trivial path $\pi = (x_0, \dots, x_\ell)$ is called a **circuit** if $x_0 = x_\ell$
- ▶ A path $\pi = (x_0, \dots, x_\ell)$ is called **elementary** if any two of its vertices are distinct (except possibly x_0 and x_ℓ): $\forall i, j \in \{0, \dots, \ell\}, i \neq j \implies x_i \neq x_j$ (where $\{i, j\} \neq \{0, \ell\}$)

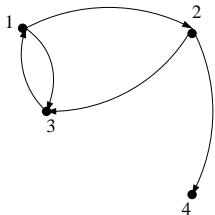


Example

- ▶ (3) is a trivial path
- ▶ $(1, 2, 3, 1)$ is a circuit that is elementary

Some remarkable paths

- ▶ A path of length 0 is called a **trivial path**
- ▶ A non-trivial path $\pi = (x_0, \dots, x_\ell)$ is called a **circuit** if $x_0 = x_\ell$
- ▶ A path $\pi = (x_0, \dots, x_\ell)$ is called **elementary** if any two of its vertices are distinct (except possibly x_0 and x_ℓ): $\forall i, j \in \{0, \dots, \ell\}, i \neq j \implies x_i \neq x_j$ (where $\{i, j\} \neq \{0, \ell\}$)



Example

- ▶ (3) is a trivial path
- ▶ $(1, 2, 3, 1)$ is a circuit that is elementary
- ▶ $(1, 3, 1, 2, 3, 1)$ is a circuit that is not elementary

Property

- ▶ *Any path π from x to y contains an elementary path from x to y*

Property

- ▶ *Any path π from x to y contains an elementary path from x to y*
- ▶ *The length of an elementary circuit is less than n (where $n = |E|$)*

Property

- ▶ *Any path π from x to y contains an elementary path from x to y*
- ▶ *The length of an elementary circuit is less than n (where $n = |E|$)*
- ▶ *The length of an elementary path which is not a circuit is less than $n - 1$*

Undirected paths and cycles

Definition

- ▶ Let $G_s = (E, \Gamma_s)$ be the symmetric closure of G

Undirected paths and cycles

Definition

- ▶ Let $G_s = (E, \Gamma_s)$ be the symmetric closure of G
- ▶ Any path in G_s is called an **undirected path (in G)**

Undirected paths and cycles

Definition

- ▶ Let $G_s = (E, \Gamma_s)$ be the symmetric closure of G
- ▶ Any path in G_s is called an **undirected path (in G)**
- ▶ A **cycle (in G)** is a circuit in G_s that does not pass twice by the same edge

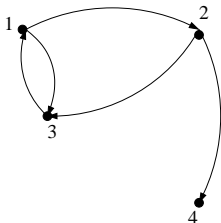
Undirected paths and cycles

Definition

- ▶ Let $G_s = (E, \Gamma_s)$ be the symmetric closure of G
- ▶ Any path in G_s is called an **undirected path (in G)**
- ▶ A **cycle (in G)** is a circuit in G_s that does not pass twice by the same edge

Remark. If $\pi = (x_0, \dots, x_\ell)$ is an undirected path, then $\pi' = (x_\ell, \dots, x_0)$ is an undirected path (since (E, Γ_s) is a symmetric graph, which implies that $x_i \in \Gamma_s(x_{i-1}) \Leftrightarrow x_{i-1} \in \Gamma_s(x_i)$)

Illustration: path and undirected path, circuit and cycles



Example

- ▶ $(1, 2, 1)$ is not a path
- ▶ $(1, 2, 3)$ is a path
- ▶ $(1, 2, 3, 1, 2, 4)$ is a path
- ▶ $(4, 2, 1)$ is not a path
- ▶ $(4, 2, 1)$ is an undirected path
- ▶ $(1, 2, 3, 1)$ is a circuit
- ▶ $(1, 3, 2, 1)$ is not a circuit
- ▶ $(1, 3, 2, 1)$ is a cycle
- ▶ $(1, 3, 1)$ is not a cycle



Programa de Pós-graduação em
INFORMÁTICA



PUC Minas



Graph-based image processing

— Connectivity —

(Professor version)

(Connectivity in graphs)

Silvio Guimarães

Graduate Program in Informatics – PPGINF

Image and Multimedia Data Science Laboratory – IMScience

Pontifical Catholic University of Minas Gerais – PUC Minas

Connected component

Definition

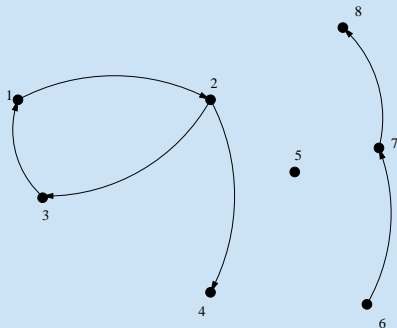
- ▶ Let $x \in E$. The **connected component of G containing x** is the subset C_x of E defined by:
 - ▶ $C_x = \{y \in E \mid \text{there exists an undirected path from } x \text{ to } y\}$

Connected component

Definition

- ▶ Let $x \in E$. The **connected component of G containing x** is the subset C_x of E defined by:
 - ▶ $C_x = \{y \in E \mid \text{there exists an undirected path from } x \text{ to } y\}$

Example



- ▶ $C_1 = \{1, 2, 3, 4\} = C_2 = C_3 = C_4$
- ▶ $C_5 = \{5\}$
- ▶ $C_6 = C_7 = C_8 = \{6, 7, 8\}$

Property

1. $\forall x \in E, x \in C_x$ **reflexivity**
2. $\forall x, y \in E, y \in C_x \implies x \in C_y$ **symmetry**
3. $\forall x, y, z \in E, [y \in C_x \text{ and } z \in C_y] \implies z \in C_x$ **transitivity**

Proof.

1. $\forall x \in E, (x)$ is a (trivial) undirected path, thus $x \in C_x$
2. $y \in C_x \implies \exists$ an undirected path $\pi = (x_0, \dots, x_\ell)$ from x to y
 $\implies \pi' = (x_\ell, \dots, x_0)$ is an undirected path from y to x
 $\implies x \in C_y$
3. $[y \in C_x \text{ and } z \in C_y] \implies [\exists$ an undirected path $\pi = (x_0, \dots, x_\ell)$ from x to y and \exists an undirected path $\pi' = (y_0, \dots, y_m)$ from y to $z] is an undirected path from x to $z \implies z \in C_x$$



Strongly connected component

Definition

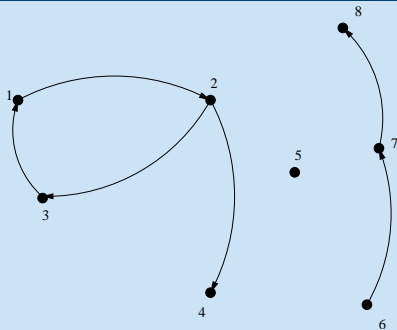
- ▶ Let $x \in E$. The **strongly connected component** (of G) containing x is the subset C'_x of E defined by
 - ▶ $C'_x = \{y \in E \mid \exists \text{ a path from } x \text{ to } y \text{ and } \exists \text{ a path from } y \text{ to } x\}$

Strongly connected component

Definition

- ▶ Let $x \in E$. The **strongly connected component** (of G) containing x is the subset C'_x of E defined by
 - ▶ $C'_x = \{y \in E \mid \exists \text{ a path from } x \text{ to } y \text{ and } \exists \text{ a path from } y \text{ to } x\}$

Example



- ▶ $C'_1 = \{1, 2, 3\} = C'_2 = C'_3$
- ▶ $C'_4 = \{4\}$; $C'_5 = \{5\}$
- ▶ $C'_6 = \{6\}$; $C'_7 = \{7\}$
- ▶ $C'_8 = \{8\}$

Exercise. Are the strongly connected components of a graph equivalence classes? Proof or counter-example?



Programa de Pós-graduação em
INFORMÁTICA



PUC Minas



Graph-based image processing

— Algorithms —

(Professor version)

(Connectivity in graphs)

Silvio Guimarães

Graduate Program in Informatics – PPGINF

Image and Multimedia Data Science Laboratory – IMScience

Pontifical Catholic University of Minas Gerais – PUC Minas

- ▶ We will first study a characterization of connected components and of strongly connected components based on **morphological dilation**
- ▶ This will allow us to propose efficient algorithm to compute them

The **morphological dilation** $\delta_r(X)$ of a subset X of E is the union of the sets of successors of all vertices in X

Iterated operators

- ▶ Let γ be an operator and $i \in \mathbb{N}$
- ▶ We denote by γ^i the **operator** defined by
 1. $\gamma^i = \gamma\gamma^{i-1}$
 2. $\gamma^0 = Id$ (i.e. $\forall X \subseteq E, \gamma^0(X) = X$)

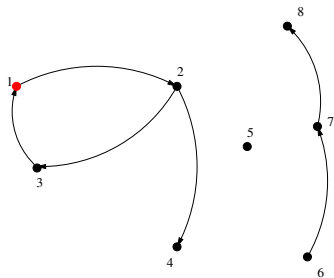
Iterated operators

- ▶ Let γ be an operator and $i \in \mathbb{N}$
- ▶ We denote by γ^i the **operator** defined by
 1. $\gamma^i = \gamma\gamma^{i-1}$
 2. $\gamma^0 = Id$ (i.e. $\forall X \subseteq E, \gamma^0(X) = X$)

Example (iterated dilation)

1. $\delta_\Gamma^0(X) = X$
2. $\delta_\Gamma^1(X) = \delta_\Gamma(\delta_\Gamma^0(X)) = \delta_\Gamma(X)$
3. $\delta_\Gamma^2(X) = \delta_\Gamma(\delta_\Gamma^1(X)) = \delta_\Gamma(\delta_\Gamma(X))$
4. $\delta_\Gamma^3(X) = \delta_\Gamma(\delta_\Gamma^2(X)) = \delta_\Gamma(\delta_\Gamma(\delta_\Gamma(X)))$
5. ...
6. $\delta_\Gamma^i(X) = \delta_\Gamma(\delta_\Gamma^{i-1}(X)) = \delta_\Gamma(\dots \delta_\Gamma(X) \dots)$

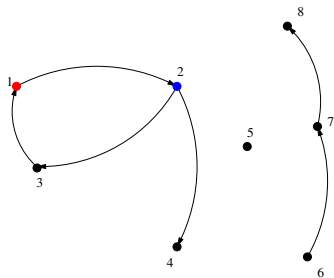
Illustration: iterated dilation



Example

► $X = \delta_1^0(X) = \{1\}$

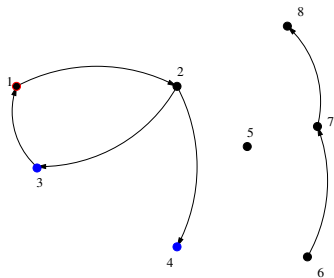
Illustration: iterated dilation



Example

- ▶ $X = \delta_1^0(X) = \{1\}$
- ▶ $\delta_1^1(X) = \{2\}$

Illustration: iterated dilation



Example

- ▶ $X = \delta_1^0(X) = \{1\}$
- ▶ $\delta_1^1(X) = \{2\}$
- ▶ $\delta_1^2(X) = \{3, 4\}$

Iterated dilation and paths of given length

Property

- ▶ Let $x \in E$ and $i \in \mathbb{N}$
- ▶ The two following equalities **hold true**
 - ▶ $\delta_T^i(\{x\}) = \{y \in E \mid \exists \text{ a path from } x \text{ to } y \text{ of length } i\}$
 - ▶ $\delta_{T^{-1}}^i(\{x\}) = \{y \in E \mid \exists \text{ a path from } y \text{ to } x \text{ of length } i\}$

Iterated dilation and paths of given length

Property

- ▶ Let $x \in E$ and $i \in \mathbb{N}$
- ▶ The two following equalities **hold true**
 - ▶ $\delta_T^i(\{x\}) = \{y \in E \mid \exists \text{ a path from } x \text{ to } y \text{ of length } i\}$
 - ▶ $\delta_{T^{-1}}^i(\{x\}) = \{y \in E \mid \exists \text{ a path from } y \text{ to } x \text{ of length } i\}$

- ▶ We define for any $X \subseteq E$ and any $p \in \mathbb{N}$
 - ▶ $\hat{\delta}_T^p(X) = \cup\{\delta_T^i(X) \mid i \in \{0, \dots, p\}\}$

Iterated dilation and paths of given length

Property

- ▶ Let $x \in E$ and $i \in \mathbb{N}$
- ▶ The two following equalities **hold true**
 - ▶ $\delta_T^i(\{x\}) = \{y \in E \mid \exists \text{ a path from } x \text{ to } y \text{ of length } i\}$
 - ▶ $\delta_{T^{-1}}^i(\{x\}) = \{y \in E \mid \exists \text{ a path from } y \text{ to } x \text{ of length } i\}$

- ▶ We define for any $X \subseteq E$ and any $p \in \mathbb{N}$
 - ▶ $\hat{\delta}_T^p(X) = \cup\{\delta_T^i(X) \mid i \in \{0, \dots, p\}\}$
- ▶ The set $\hat{\delta}_T^p(X)$ is called the **pre-closure of X of rank p**

Transitive closure and paths

Corolary

- ▶ Let $x \in E$
- ▶ The two following equalities **hold true**
 - ▶ $\hat{\delta}_T^p(\{x\}) = \{y \in E \mid \exists \text{ a path from } x \text{ to } y \text{ of length } \leq p\}$
 - ▶ $\hat{\delta}_{T^{-1}}^p(\{x\}) = \{y \in E \mid \exists \text{ a path from } y \text{ to } x \text{ of length } \leq p\}$

Transitive closure and paths

Corolary

- ▶ Let $x \in E$
- ▶ The two following equalities **hold true**
 - ▶ $\hat{\delta}_G^p(\{x\}) = \{y \in E \mid \exists \text{ a path from } x \text{ to } y \text{ of length } \leq p\}$
 - ▶ $\hat{\delta}_{G^{-1}}^p(\{x\}) = \{y \in E \mid \exists \text{ a path from } y \text{ to } x \text{ of length } \leq p\}$

- ▶ Let $x \in E$, the **(transitive) closure of $\{x\}$** is the set
- ▶ $\hat{\delta}_G^\infty(\{x\}) = \{y \in E \mid \exists \text{ a path from } x \text{ to } y\}$

Transitive closure and paths

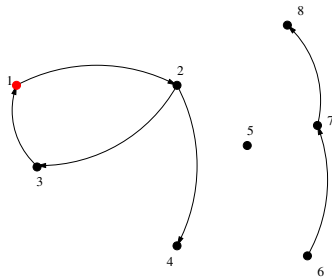
Corollary

- ▶ Let $x \in E$
- ▶ The two following equalities **hold true**
 - ▶ $\hat{\delta}_T^p(\{x\}) = \{y \in E \mid \exists \text{ a path from } x \text{ to } y \text{ of length } \leq p\}$
 - ▶ $\hat{\delta}_{T^{-1}}^p(\{x\}) = \{y \in E \mid \exists \text{ a path from } y \text{ to } x \text{ of length } \leq p\}$

- ▶ Let $x \in E$, the **(transitive) closure of $\{x\}$** is the set
- ▶ $\hat{\delta}_T^\infty(\{x\}) = \{y \in E \mid \exists \text{ a path from } x \text{ to } y\}$

Exercise. Prove that $\hat{\delta}_T^\infty(\{x\}) = \hat{\delta}_T^{n-1}(\{x\})$ (where $n = |E|$)

Illustration: transitive closure

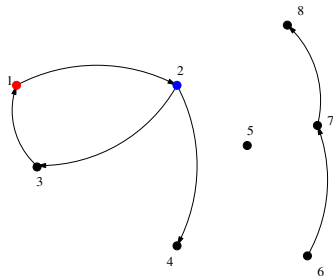


Example

▶ $X = \delta_r^0(X) = \{1\}$

▶ $X = \hat{\delta}_r^0(X) = \{1\}$

Illustration: transitive closure



Example

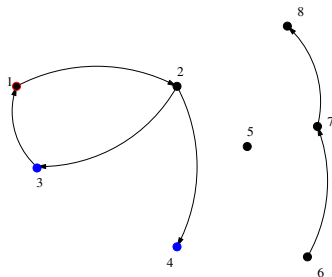
▶ $X = \delta_r^0(X) = \{1\}$

▶ $\delta_r^1(X) = \{2\}$

▶ $X = \hat{\delta}_r^0(X) = \{1\}$

▶ $\hat{\delta}_r^1(X) = \{1, 2\}$

Illustration: transitive closure



Example

▶ $X = \delta_r^0(X) = \{1\}$

▶ $\delta_r^1(X) = \{2\}$

▶ $\delta_r^2(X) = \{3, 4\}$

▶ $X = \hat{\delta}_r^0(X) = \{1\}$

▶ $\hat{\delta}_r^1(X) = \{1, 2\}$

▶ $\hat{\delta}_r^2(X) = \{1, 2, 3, 4\} = \hat{\delta}_r^7(X)$

Property

- ▶ Let $x \in E$. Let C_x and C'_x be respectively the **connected components** and the **strongly** connected components containing x

Property

- ▶ Let $x \in E$. Let C_x and C'_x be respectively the **connected components** and the **strongly** connected components containing x
- ▶ The two following equalities **hold true**
 - ▶ $C'_x = \delta_{\Gamma}^{\hat{n}-1}(\{x\}) \cap \delta_{\Gamma^{-1}}^{\hat{n}-1}(\{x\})$
 - ▶ $C_x = \delta_{\Gamma_s}^{\hat{n}-1}(\{x\}) = \delta_{\Gamma_s}^{\hat{n}-1}(\{x\})$
- ▶ where $n = |E|$ and Γ_s is the symmetric closure of Γ

Property

- ▶ Let $x \in E$. Let C_x and C'_x be respectively the **connected components** and the **strongly** connected components containing x
 - ▶ The two following equalities **hold true**
 - ▶ $C'_x = \delta_{\Gamma}^{\hat{n}-1}(\{x\}) \cap \delta_{\Gamma^{-1}}^{\hat{n}-1}(\{x\})$
 - ▶ $C_x = \delta_{\Gamma_s}^{\hat{n}-1}(\{x\}) = \delta_{\Gamma_s^{-1}}^{\hat{n}-1}(\{x\})$
 - ▶ where $n = |E|$ and Γ_s is the symmetric closure of Γ
-
- ▶ To compute the connected and strongly connected components containing x , it is thus **sufficient to compute** the transitive closure of $\{x\}$ for the graphs (E, Γ) , (E, Γ^{-1}) and (E, Γ_s)

Algorithm TRANS_NAIV (**Data:** $(E, \Gamma), x \in E$;

Results: $Z = \delta_{\Gamma}^{\hat{n}-1}(\{x\})$

- ▶ $X := \{x\}$; $Y := \emptyset$; $Z := \{x\}$;
- ▶ **For each** i **from** 1 **to** $n - 1$ **do**
 - ▶ $Y := \text{DIL}((E, \Gamma), X)$;
 - ▶ $Z := Z \cup Y$;
 - ▶ $X := Y$; $Y := \emptyset$;

/* $Y = \delta_{\Gamma}^i(\{x\})$ */

/* $Z = \hat{\delta}_{\Gamma}^i(\{x\})$ */

Naive algorithm for the transitive closure of $\{x\}$

Algorithm TRANS_NAIV (**Data:** $(E, \Gamma), x \in E$;

Results: $Z = \delta_{\Gamma}^{\hat{n}-1}(\{x\})$

- ▶ $X := \{x\}$; $Y := \emptyset$; $Z := \{x\}$;
- ▶ **For each** i from 1 to $n - 1$ **do**
 - ▶ $Y := \text{DIL}((E, \Gamma), X)$; /* $Y = \delta_{\Gamma}^i(\{x\})$ */
 - ▶ $Z := Z \cup Y$; /* $Z = \hat{\delta}_{\Gamma}^i(\{x\})$ */
 - ▶ $X := Y$; $Y := \emptyset$;

Complexity

- ▶ *By using the algorithm DIL studied during practical session # 1*
- ▶ *The complexity of TRANS_NAIV is*
 - ▶ $O(n^2 + nm)$ (where $n = |E|$ and $m = |\bar{\Gamma}|$)

Algorithm TRANS (Data: $(E, \Gamma), x \in E$;

Result: $Z = \delta_{\Gamma}^{\hat{n}-1}(\{x\})$)

$X := \{x\}$; $Y := \emptyset$; $Z := \{x\}$;

For each i from 1 to $n - 1$ **do**

▶ **While** $\exists y \in X$ **do**

▶ $X := X \setminus \{y\}$;

▶ **For each** $z \in \Gamma(y)$ **do**

▶ **If** $z \notin Z$ **then** $Y := Y \cup \{z\}$; $Z := Z \cup \{z\}$;

▶ $X := Y$; $Y := \emptyset$;

Algorithm TRANS (Data: $(E, \Gamma), x \in E$;

Result: $Z = \delta_{\Gamma}^{\hat{n}-1}(\{x\})$

$X := \{x\}$; $Y := \emptyset$; $Z := \{x\}$;

For each i from 1 to $n - 1$ **do**

▶ **While** $\exists y \in X$ **do**

▶ $X := X \setminus \{y\}$;

▶ **For each** $z \in \Gamma(y)$ **do**

▶ **If** $z \notin Z$ **then** $Y := Y \cup \{z\}$; $Z := Z \cup \{z\}$;

▶ $X := Y$; $Y := \emptyset$;

- ▶ If X and Y are represented by LLs and if Z is represented by a BA
- ▶ The time-complexity of TRANS is linear
 - ▶ $O(n + m)$ (where $n = |E|$ and $m = |\bar{\Gamma}|$)

Algorithm TRANS can be further **simplified** without changing its complexity:

Algorithm TRANS (**Data:** $(E, \Gamma), x \in E$;

Result : $Z = \delta_r^{\hat{n}-1}(\{x\})$

- ▶ $X := \{x\}$; $Z := \{x\}$;
- ▶ **While** $\exists y \in X$ **do**
 - ▶ $X := X \setminus \{y\}$;
 - ▶ **For each** $z \in \Gamma(y)$ **do**
 - ▶ **If** $z \notin Z$ **then** $X := X \cup \{z\}$; $Z := Z \cup \{z\}$;

Algorithm SCC (Data: $(E, \Gamma), x \in E$;

Result: $Z = C'_x$)

- ▶ $X := \text{TRANS}((E, \Gamma), x)$;
- ▶ $\Gamma^{-1} := \text{SYM_1}(E, \Gamma)$;
- ▶ $Y := \text{TRANS}((E, \Gamma^{-1}), x)$
- ▶ $Z := X \cap Y$;

Algorithm SCC (Data: $(E, \Gamma), x \in E$;

Result: $Z = C'_x$)

- ▶ $X := \text{TRANS}((E, \Gamma), x)$;
- ▶ $\Gamma^{-1} := \text{SYM_1}(E, \Gamma)$;
- ▶ $Y := \text{TRANS}((E, \Gamma^{-1}), x)$
- ▶ $Z := X \cap Y$;

▶ Using

- ▶ the linear-time algorithm SYM_1 (first lecture)
- ▶ the linear-time TRANS
- ▶ The time-complexity of SCC is linear:
 - ▶ $O(n + m)$ (where $n = |E|$ and $m = |\bar{\Gamma}|$)

Algorithm CC (Data: $(E, \Gamma), x \in E$;

Result: $Y = C_x$)

- ▶ $\Gamma^{-1} := \text{SYM_1}(E, \Gamma)$;
- ▶ $\Gamma_s := \Gamma \cup \Gamma^{-1}$;
- ▶ $Y := \text{TRANS}((E, \Gamma_s), x)$

Algorithm CC (Data: $(E, \Gamma), x \in E$;

Result: $Y = C_x$)

- ▶ $\Gamma^{-1} := \text{SYM_1}(E, \Gamma)$;
- ▶ $\Gamma_s := \Gamma \cup \Gamma^{-1}$;
- ▶ $Y := \text{TRANS}((E, \Gamma_s), x)$

▶ Using

- ▶ the linear-time algorithm SYM_1 (first lecture)
- ▶ the linear-time TRANS

▶ The time-complexity of CC is linear:

- ▶ $O(n + m)$ (where $n = |E|$ and $m = |\bar{\Gamma}|$)



Programa de Pós-graduação em
INFORMÁTICA



PUC Minas



Graph-based image processing

— Degrees —

(Professor version)

(Connectivity in graphs)

Silvio Guimarães

Graduate Program in Informatics – PPGINF

Image and Multimedia Data Science Laboratory – IMScience

Pontifical Catholic University of Minas Gerais – PUC Minas

Problem

- ▶ *In a charity diner, is there always two people having the same number of friends who are present in the diner?*
- ▶ *Can we draw in the plan five distinct lines such that any of them has exactly three intersection points with the others?*

Problem

- ▶ *In a charity diner, is there always two people having the same number of friends who are present in the diner?*
 - ▶ *Can we draw in the plan five distinct lines such that any of them has exactly three intersection points with the others?*
- ▶ In order to answer these questions read first the two next slides!

- ▶ Let $G = (E, \Gamma)$ be a graph and let $x \in E$
- ▶ The **outer degree of x (for G)** is the value $d^+(x) = |\Gamma(x)|$
- ▶ The **inner degree of x (for G)** is the value $d^-(x) = |\Gamma^{-1}(x)|$
- ▶ The **degree of x (for G)** is the value $d(x) = d^+(x) + d^-(x)$
- ▶ Let $G' = (E, \bar{\Gamma})$ be an undirected graph
- ▶ The **degree of x for G'** is the number $d(x)$ of edges that are adjacent to x

- ▶ Prove that the two following propositions hold true
 - ▶ The sum of the degrees of the vertices of a graph is even
 - ▶ In any graph, there is an even number of vertices whose degree is odd

Acknowledgement

Thanks to the Prof. Jean Cousty at ESIEE/France that gently sent me the slides used in the Morpho, Graph and Image course. Some slides of the Graph-based Image Processing course at PPGINF/PUC Minas under supervision of Prof. Silvio Guimarães will be adapted versions of that course.

- ▶ Course - MorphoGraph and Imagery
<https://perso.esiee.fr/coustyj/EnglishMorphoGraph/>
- ▶ Jean Cousty
 - ▶ ESIEE Paris, Département Informatique
 - ▶ Université Paris-Est, LIGM (UMR CNRS, ESIEE...)
 - ▶ E-mail: j.cousty@esiee.fr